Steganalysis Algorithm for Edge Adaptive Least Significant Bit Matching Revisited Detection

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INTRODUCTION

Steganography technology is an important branch in the field of information security, and its main purpose is to hide the secret to be transmitted in the carrier object with some technical means and not arouse the suspicions of the third party. The carrier for the secret information has a variety of forms, such as digital image, video, audio, and text files. Steganalysis technology is the opposite of Steganography technology, and its main purpose is to detect whether secret information is hidden in the carrier file. Steganography technology and Steganalysis technology are unity of opposites, contradictory and dependent on each other. With the increasingly widely application of information security technology, steganography technology and Steganalysis technology have enjoyed fast growth. In the field of information hiding, the digital image in spatial domain is easy to operate, can be embedded with large capacity and can be applied widely; Steganography technology and Steganalysis technology which are based on the technology of digital image spatial domain secret and hidden analysis technology receive rapid development.

Least Significant Bit (LSB) Replacement (Chandramouli et al., 2003) is the earliest spatial domain Steganography technology, and reaches the purpose of embedding secret information by directly reversing the lowest significance bit of grayscale value which is different from the secret information bit value (Bender et al., 1996). But this change will bring image pixel gray value histogram obvious "value effect", so the LSB replacement of algorithm secret will soon be breached, Steganalysis algorithm such as Chi - square (Westfeld and Pfitzmann, 2000) and (Fridrich et al., 2001; Fridrich and Goljan 2002) RS detection, WS test (Schottle et al., 2012) and AUMP test (Fillatre, 2012), etc. can effectively detect LSB replacement hiding algorithm. Compared to the LSB hiding algorithm, LSB matching (Least Significant Bit Matching) (Sharp, 2001) hiding algorithm has a qualitative change. LSB matching algorithm was not regularly on the lowest effective pixels directly, but a plus or minus 1 at random. This kind of operation avoids the "value effect" in the LSB replacement algorithm. But LSB matching algorithm has its own weaknesses, the algorithm embedded mechanism destroys the natural images of smooth area of the correlation of adjacent pixels, making the adjacent pixels have the characteristics of independence, which is impossible in the smooth area of the original natural images, and thus the LSB matching algorithm is also be breached by a variety of hidden analysis algorithm (Harmsen and Pearlman, 2003; Cancelli et al., 2008; Goljan et al., 2006; Ker, 2005). LSB matching revisited (LSBMR) [1] uses a pair of pixels as an embedding unit, in which the LSB of the first pixel carries one bit of secret message, and the relationship...
of the two pixel values carries another bit of secret message. Luo et al., (2010) presented a new spatial domain LSB matching steganography algorithm (Edge Adaptive LSB Matching Revisited, referred EALMR). EALMR steganography algorithm is high safety spatial domain information hiding techniques which can choose embedding area based on the image context. Embedding area by choosing the area with rich texture can reduce the change of statistical features brought by the information embedding message process. This adaptive advantage of EALMR can make it has stronger security. HUGO (Pevny et al., 2010) is by far the most secure coding techniques based on steganography algorithm, its security comes from the self-adaptive mechanism of embedding information. When use HUGO algorithm to embed information, STC (Syndrome-Trellis Codes) (Filler et al., 2010; Filler et al., 2011) is applied, the best embedding path can be found by calculating the embedding distortion in order to minimize the effects brought by embedding of information. Also, it can also effectively avoid the wet points in wet paper coding. Currently, there are no analysis algorithms to detect EA algorithm and HUGO algorithm, but relevant research work has been made some meaningful progress (Fridrich et al., 2011; Fridrich et al., 2011; Gul and Kurugollu, 2011).

In the areas of steganalysis techniques, as for the features of spatial domain steganography algorithm, many algorithms are proposed to detect Steganography algorithms. Harmensen and Pearlman proposed a histogramcharacteristic function centroid (Histogram Characteristic Function-Center of Mass, HCF-COM) Steganalysis algorithm method (Harmensen and Pearlman, 2003). In this algorithm, histogram characteristic function is the Discrete Fourier Transform of histogram image. It can detect by comparing HCF-COM of images and calibrated images. But as the different carrier images’ HCF-COM vary, sometimes even more than the difference brought by the secret information embedding process. As a result, directly comparison of HCF-COM to judge whether the image has the information hiding dose not perform well. Goljan et al., (2006) proposed Wavelet Absolute Moment (WAM) Steganalysis algorithm method. Firstly, it moves the Gaussian noise to increase the signal to noise ratio, then it exacts noise component of small wave area of secret images as the features for analyzing secrets. Suppose the original image is non-stationary Gaussian signal, the noise is the smooth Gaussian signal with known variance, the secret image can be the sum of both. When image information is hidden by the LSBM algorithm, its local minimum value of the histogram increases and the local maxima value decreases. Based on this principle, Zhang et al., (2007) proposed to use the sum of Amplitude of Histogram Local Extrema as the features for analyzing secrets. However, the algorithm does not consider the case of the boundary points in the histogram, when the gray value is 0, 1 only can be changed to 1, when the gray value is 255, and it can be changed to 254. Based on this, Cancell et al improved the ALE analysis algorithm (Cancelli et al., 2008) and consider individually the boundary points [1,2,253,254]; two-dimensional histogram local extrema amplitude characteristics is added on the original base. The sum of diagonal elements of two-dimensional histogram is added as the features. Pevny et al., (2009) proposed Subtractive Pixel Adjacency Model (SPAM) Steganalysis algorithm method. It calculates the eight directions of absolute difference of horizontal, vertical, main diagonal and sub diagonal directions in the grayscale matrix. Then use Markov to build models for these grayscale matrixes. They use one-step and two -step transition probability matrix as the features for analyzing secrets. At the same time, by setting an appropriate threshold to reduce the feature dimension, the computational complexity becomes more reasonable. Fridrich and Kodovsky, (2012) proposed a rich model airspace Steganalysis algorithm method. This algorithm extracts various characteristics from the airspace and forms a plurality of feature subset. These features set contain all the features, which are useful for the analysis of airspace. Various steganalysis algorithm method can achieve very good results in the detection of LSB replacement and LSB Matching algorithms, but they cannot detect EALMR algorithm and HUGO algorithm.

The rest of this paper is organized as follows: the first section explains materials and methods, which contains Edge Adaptive LSB Matching Revisited algorithm and the proposed algorithm. The second section explains results and discussion. The final section concludes the paper.

**MATERIALS AND METHODS**

**A. Edge Adaptive LSB Matching Revisited:**

In digital gary-level image, the absolute difference of pixel couple \((x_i, x_{i+1})\) is indicated as:

\[
d = |x_{i+1} - x_i|
\]  

(1)

It is hereby to restate Information Embedding Mechanism and Data Readjusting Mechanism in EALMR:

**A. Information Embedding Mechanism:**

For the pixel couples in VI SetEU(t) = \(\{(x_i, x_{i+1})|x_i - x_{i+1} \geq t, \forall (x_i, x_{i+1}) \in V\}\) that conforms to embedding conditions, the information will be embedded in couples according to traversial order determined by Secret Key 2 and each couple of U elements will hide 2 bits of secret information. According to relational difference between pixel value and secret information, the specific embedding mechanism can be divided into 4 cases, as follows:
Case #1: LSB($x_i$) = $m_i$ & $f(x_i, x_{i+1}) = m_{i+1}$
($x'_i, x'_{i+1}$) = ($x_i, x_{i+1}$)
Case #2: LSB($x_i$) = $m_i$ & $f(x_i, x_{i+1}) \neq m_{i+1}$
($x'_i, x'_{i+1}$) = ($x_i, x_{i+1}$)

Case #3: LSB($x_i$) = $m_1$ & $f(x_i - 1, x_{i+1}) = m_{i+1}$
($x'_i, x'_{i+1}$) = ($x_i - 1, x_{i+1}$)
Case #4: LSB($x_i$) = $m_i$ & $f(x_i - 1, x_{i+1}) \neq m_{i+1}$
($x'_i, x'_{i+1}$) = ($x_i + 1, x_{i+1}$)

In these formulas, $m_i$ and $m_{i+1}$ refer to secret information to be embedded into the pixel couple ($x_i, x_{i+1}$), and ($x'_i, x'_{i+1}$) refers to secret-held pixel couple after the secret information is embedded; $r$ random refers to $+1$ or $-1$, and the $f(a, b)$ is defined as follows:

$$f(a, b) = \text{LSB}\left(\left\lfloor \frac{a}{2} \right\rfloor + b \right)$$

### A.ii Data Readjusting Mechanism:

If the secret-held pixel couple ($x'_i, x'_{i+1}$) does not conform to $|x'_i - x_{i+1}| \geq T$, or $x'_i$ and $x'_{i+1}$ go beyond [0, 255], it is required to apply Data Readjusting Mechanism in the following readjustment formula:

$$(x'_i, x'_{i+1}) = \text{argmin}_{(x, y)} \{e_1 + e_2 | e_1 = x - 4k_1, e_2 = x_{i+1} - 255 \text{ or } e_1 + e_2 = 255 \text{ or } 0 \leq e_1, e_2 \leq 31, k_1, k_2 \in \mathbb{Z}\}$$

As readjusted in the formula above, $0 \leq x'_i, x'_{i+1} \leq 255$ and $|x'_i - x'_{i+1}| \geq T$ can be ensured.

### B. Proposed Algorithm:

In embedding mechanism, it is assumed that four embedding cases respectively occur at the same probability of 0.25. In Case #1, the pixel couple is not changed, so the absolute difference of pixel couple after information embedding will not be changed. For such other three cases as Case #2, Case #3 and Case #4, the probability of pixel couple resulted after information embedding, that conforms to $|x_i - x_{i+1}| = T - 1$ or $|x_i - x_{i+1}| = T + 1$, is 0.5. Therefore, the probability of absolute difference of pixel couple, after information embedding, that changes from T-1 to T-1 or T+1, is 0.75x0.5 = 0.375. If the pixel couple resulted after first information embedding conforms to $|x_i - x_{i+1}| < T$ the data readjusting mechanism will apply, so the pixel couple whose absolute difference changes to T-1 will be subject to data readjusting mechanism. It is further analyzed that when the pixel couple is selected for information embedding the precondition of the $|x_i - x_{i+1}| \geq T$is required to be met and that each pixel couple in EALMR has at most one pixel to be added or reduced by 1, so the $|x_i - x_{i+1}| < T$ only occurs under the condition of $|x_i - x_{i+1}| = T$ and $|x_i - x_{i+1}| = T - 1$. However, $|x_i - x_{i+1}| = T - 1$ has four cases, including two cases for $x_i - x_{i+1} = T - 1$ and two cases for $x_i - x_{i+1} = T - 1$:

1. When $x_i - x_{i+1} = T - 1$ and $x_{i+1} \geq 2$, after data readjusting, the case is $k_1 = 0$ and $k_2 = -1$;
2. When $x_i - x_{i+1} = T - 1$ and $0 \leq x_{i+1} < 2$, the case is $k_1 = 1$ and $k_2 = 0$;
3. When $x_i - x_{i+1} = T - 1$ and $x_{i+1} \leq 253$, after data readjusting, the case is $k_1 = 0$ and $k_2 = 1$;
4. When $x_i - x_{i+1} = T - 1$ and $253 < x_{i+1} \leq 255$, the case is $k_1 = -1$ and $k_2 = 0$.

When the data readjusting mechanism is adopted, $k_1$ and $k_2$ under the influence of formula (3), will be further limited by the extraction formula of secret information in the algorithm. In EALMR, the extraction principle of secret-information

$$m_i = \text{LSB}(x'_i), m_{i+1} = f(x'_i, x'_{i+1}) = \text{LSB}\left(\left\lfloor \frac{x'_i}{2} \right\rfloor + x'_{i+1}\right).$$

So, the formula should be adjusted by $e_1 = x'_i + 4k_1, e_2 = x_{i+1} + 2k_2, k_1, k_2 \in Z$. From the four cases of embedding mechanism, $x'_i - x'_{i+1} = T - 1$ only occurs under Case #1, Case #2 and Case #3. It is assumed that $x_i = x_i + r_1, x_{i+1} = x_{i+1} + r_2$. $x_i = x_i + 4k_1, x_{i+1} = x_{i+1} + 2k_2$. Therefore, the $|e_1 - x_i| + |e_2 - x_{i+1}|$ in the data readjusting mechanism can be represented by the following:

$$|e_1 - x_i| + |e_2 - x_{i+1}| = |x_i + 4k_1 - x_i| + |x_{i+1} + 2k_2 - x_{i+1}|$$

$$= |4k_1 + r_1| + |2k_2 + r_2|$$

In the only event that data readjusting mechanism is applied under Case #1 and Case #2, according to the principle of embedding mechanism, each pixel-couple has only one pixel to be added or reduced by 1, whereby the $r_1$ and $r_2$ conform to $r_1, r_2 \in \{0, -1, +1\}$ and $|r_1| + |r_2| = 1$. The absolute difference of pixel couple changed in data readjusting mechanism is no less than T on the condition that $r_1$ and $r_2$ conform to $|r_1| + |r_2| \neq 0$. The following process of proof for $k_1$ and $k_2$ shall be represented by such two processes of proof as $x_i - x_{i+1} = T - 1$ and $x_i - x_{i+1} = T - 1$.

1. When $x_i - x_{i+1} = T - 1$: $x_i - x_{i+1} = T - 1$ and $x_{i+1} \geq 2$ only occurs under $x'_i = x_i - 1$ (Case #3) or $x'_{i+1} = x_{i+1} + 1$ (Case #2), so $r_1 = -1, r_2 = 0$ (Case #3) or $r_1 = 0, r_2 = 1$ (Case #2). Based on the formula (4)
and \(|k_1| + |k_2| \neq 0\), in such two cases, \(k_1=0\) and \(k_2 = -1\). On the condition of \(x_i' = x_i - 1\) (Case #3), although \(k_2 = 1\) also conforms to the requirement of formula (4) under \(r_1 = -1, r_2 = 0\) (Case #3), in order to conform to \(x_{i+1}' - x_i' = T\), the case is \(k_2 \neq 1\).

For the case of \(x_i' = x_{i+1}' = T - 1\) and \(x_{i+1}' < 2\), \(x_{i+1}'' = x_{i+1}' + 2k_2\), so \(k_2 \neq 1\), which means that \(k_2\) could only be 0 or 1. Based on formula (4) and \(|k_1| + |k_2| \neq 0\), where \(r_1 = -1, r_2 = 0\) (Case #3), if \(k_2 = 0\) and \(k_1 = 1\), the only and minimal of formula (4) will be 3, and the case is \(x_i - x_{i+1} = T + 3\); if \(k_2 = 1\) and \(k_1 = 0\), the only and minimal of formula (4) will still be 3, but the \(x_i - x_{i+1} = T - 3\) does not meet the preconditions of this algorithm. Therefore, the case is \(k_1=1,k_2=0\) and \(x_i - x_{i+1} = T + 3\). Where \(r_1=0, r_2=1\) (Case #2), if \(k_2=0\) and \(k_1=1\), the only and minimal of formula (4) will be 5; if \(k_2=1\), the case is \(x_i - x_{i+1} = T + 3\) and if \(k_1=-1\), the case if \(x_i' = x_{i+1}' = T - 3\). Therefore, the case is \(k_1 = 1\); if \(k_2 = 1\) and \(k_1=0\), the only and minimal of formula (4) will be 3 and the case is \(x_i' - x_{i+1}' = T + 3\). Therefore, the final case is \(k_1 = 1, k_2 = 0\) and \(x_i' - x_{i+1}' = T + 3\).

II) Where \(x_i' - x_i = T - 1\): The case of \(x_{i+1}' - x_i' = T - 1\) and \(x_{i+1}' \leq 253\) only occurs under condition of \(x_i' = x_i - 1\) (Case #4) or \(x_{i+1}' = x_{i+1} - 1\) (Case #2). Therefore, the case is \(r_1 = 1, r_2 = 0\) (Case #4) or \(r_1 = 0, r_2 = -1\) (Case #2). Based on formula (4) and \(|k_1| + |k_2| \neq 0\), in such two cases \(k_1=0\) and \(k_2=1\). In case of \(x_i' = x_i - 1\) (Case #3), although the case of \(r_1 = 1\), \(r_2 = 0\) (Case #4) and \(k_2 = -1\) also meets the requirements of formula (4), to meet \(x_{i+1}' - x_i' \geq T\), \(k_2 \neq -1\).

For the case of \(x_{i+1}' - x_i = T - 1\) and \(x_{i+1}' > 253, x_{i+1}'' = x_{i+1}' + 2k_2\), so \(k_2 \neq 1\), which means that the \(k_2\) can only be 0 or -1. Based on formula (4) and \(|k_1| + |k_2| \neq 0\), where \(r_1 = 1\) and \(r_2 = 0\) (Case #4), if \(k_2=0\) and \(k_1 = -1\), the only and minimal value of formula (4) is 3 and the case is \(x_{i+1}' - x_i' = T + 3\); if \(k_2 = -1\) and \(k_1 = 0\), the only and minimal value of formula (4) is 3 but the \(x_{i+1}' - x_i' = T + 3\) does not conform to the preconditions of the algorithm. Therefore, the case is \(k_1 = -1, k_2 = 0\) and \(x_{i+1}' - x_i' = T + 3\). Where \(r_1 = 0\) and \(r_2 = -1\) (Case #2), if \(k_2=0\) and \(k_1 = \pm 1\), the only and minimal value of formula (4) is 5; if \(k_1=1, k_2=-1\), the case is \(x_{i+1}' - x_i' = T - 3\) and if \(k_1 = -1\), the case is \(x_{i+1}' - x_i' = T + 3\). Therefore, the case \(k_1 = -1\); if \(k_2 = -1\) and \(k_1 = 0\), the only and minimal value of formula (4) is 3, and the case is \(x_{i+1}' - x_i' = T - 3\). Therefore the final case is \(k_1 = -1, k_2 = 0\) and \(x_{i+1}' - x_i' = T + 3\).

For all above, where \(x_i' = x_{i+1}' = T - 1\) and \(x_i' \geq 2\), \(k_0 = 0, k_2 = -1\) and \(|x_i' - x_{i+1}''| = T + 1\); where \(x_{i+1}' - x_i' = T - 1\) and \(x_{i+1}' \leq 253\), \(k_1 = 0, k_2 = 1\) and \(|x_i' - x_{i+1}'| = T + 1\); these are prevailing cases in EALMR, which bring significant statistical changes to stego images.

Through the analysis above, it can be seen that if the data readjusting mechanism in the EALMR makes effects, the number of pixel couples in the images, whose absolute difference is T, will change, which means that the absolute difference of some pixel couples will become T+1, such changing probability is up to 0.75. Hence, this algorithm respectively analyzes the horizon and vertical histograms of absolute difference of adjacent pixels for the purpose of EALMR detection. Fig. 1 and Fig. 2 show the original carrier image and the stego image after the information is embedded as well as its horizon and vertical histograms of absolute difference of adjacent pixels. It can be seen from Fig. 1 and Fig. 2 that, after the information is embedded through EALMR, the stego information is not such changed visually compared with the original carrier image, but there are obvious pulse distortions in the long tails of horizon and vertical histograms of absolute difference of adjacent pixels.

Therefore, for a given image A, if there is a pulse point found in its histograms of absolute difference of adjacent pixels, the image will be identified as a EA stego image; if there’s isn’t, the image will be identified as a non-EA stego image.

(a) The horizon histogram of the absolute difference of adjacent pixels
(b) The vertical histograms of the absolute difference of adjacent pixels.

**Fig. 1:** Original carrier image vegetable.

(a) The horizon histograms of the absolute difference of adjacent pixels.

(b) The vertical histograms of the absolute difference of adjacent pixels.

**Fig. 2:** EA stego image vegetable.
To further analyze Fig. 1 and Fig. 2, it is not hard to see that the distortions in Fig. 2(a) and Fig. 2(b) occur at 18 on the x ordinate, namely $T+1=18$, so it can estimated that the threshold $T\leq 17$ is used for embedding EA secrete information of the Party regulations into such image. The proposed steg analysis algorithm allows not only to directly analyze whether the secret information is embedded into the image through EALMR but to estimate the threshold $T$. However, there is a kind of image, into which the information is embedded through EALMR, and the statistical properties of its horizon and vertical histograms of absolute difference of adjacent pixels keep the same. Fig. 3 and Fig. 4 show the original carrier image that has such above special circumstance and the stego image after the information is embedded as well as its horizon and vertical histograms of absolute difference of adjacent pixels.

![Histograms](image.png)

(a) The horizon histograms of the absolute difference of adjacent pixels

(b) The vertical histogram of the absolute difference of adjacent pixels

Fig. 3: Original carrier image flower.
RESULTS AND DISCUSSIONS

From Fig. 3 and Fig. 4, after the EA secret information of the Party regulations is embedded into the original image Flower, there is no obvious change both of histograms of absolute differences of horizontally and vertically adjacent pixels, neither the pulse distortion that should exist in the long tail. If these images are selected for EA embedding, the detection will fail.

The image pool for experiments is BOSSbase ver.0.92, including 9,074 grey pgm images with resolution of 512x512. EALMR is applied for images by embedding 5%, 10%, 20%, 30%, 40% and 50% of secret information to respectively form stego image pools with different embedding rates. The statistical analysis can be directly carried out for images to be tested based on the analysis method of histogram of absolute difference of adjacent pixels, the test effect will be determined on the Average Accuracy. The higher the Average
Accuracy is, the better the test effect is. Five airspace steganalysis algorithms such as WAM, improved HCF, ALE, SPAM and SRM are used for comparison.

Fig. 5 shows the original image of the tested image Piazza and its horizon and vertical histograms of the absolute difference of adjacent pixels; Fig. 6 shows the EA stego image (embedding rate 10%) and its horizon and vertical histograms of the absolute difference of adjacent pixels; Fig. 7 shows the EA stego image (embedding rate 50%) and its horizon and vertical histograms of the absolute difference of adjacent pixels. Image Piazza has both smooth area and rich area and is typical, so it is selected to be the typical image to be tested. Tab. 1 gives the test results of five steganalysis algorithms and the new proposed steganalysis algorithm based on the histogram of the absolute difference of adjacent pixels to EALMR. Tab 2 gives the accuracy rate of estimated threshold, which is calculated by the way that, for each EA stego image, if the estimated threshold is consistent with the actual threshold in image, the estimation is correct and the final accuracy rate the percentage of correct estimated images into the total images to be tested, subject to the average of results of ten repetitive experiments.

(a) Horizon histograms of the absolute difference of adjacent pixels

(b) Vertical histograms of the absolute difference of adjacent pixels

Fig. 5: Original image of the tested image Piazza.
Fig. 6: EA stego image of the tested image Piazza (10%)
From the places of the pulse distortion in Fig. (a) (b) and Fig. 7 (a) (b), it can be seen that where the embedding rate is 10% the threshold used for information embedding is \( T = 24 \); where the embedding rate is 50% the threshold used for information embedding is \( T = 2 \). It is visible that when the lower the embedding rate is the larger the threshold is, the generated EA stego image is safer; when the higher embedding rate is the smaller the threshold value is, the generated EA stego image is less safe. In addition, it is not hard to see from the experimental result figure that the pulse distortion height of stego image where the embedding rate is 50% is higher than that where the embedding rate is 10%. This is because, in the image Piazza, pixel-couple absolute difference is generally small, and minority of pixel couples have large absolute difference. Therefore, when the embedding rate significantly increases, the values of the threshold \( T \) will greatly decrease accordingly.

Table 1: Test results.

<table>
<thead>
<tr>
<th>Embedding rate (%)</th>
<th>WAM method</th>
<th>HCF calibration method</th>
<th>ALE method</th>
<th>SPAM algorithm</th>
<th>SRM algorithm</th>
<th>Proposed algorithm</th>
</tr>
</thead>
<tbody>
<tr>
<td>5</td>
<td>51.30%</td>
<td>49.78%</td>
<td>50.04%</td>
<td>51.41%</td>
<td>53.13%</td>
<td>97.50%</td>
</tr>
<tr>
<td>10</td>
<td>52.95%</td>
<td>51.40%</td>
<td>52.56%</td>
<td>53.36%</td>
<td>56.88%</td>
<td>98.10%</td>
</tr>
<tr>
<td>20</td>
<td>55.28%</td>
<td>54.59%</td>
<td>57.26%</td>
<td>56.82%</td>
<td>70.05%</td>
<td>98.25%</td>
</tr>
<tr>
<td>30</td>
<td>60.82%</td>
<td>56.32%</td>
<td>58.79%</td>
<td>61.76%</td>
<td>77.32%</td>
<td>99.45%</td>
</tr>
<tr>
<td>40</td>
<td>65.80%</td>
<td>63.28%</td>
<td>66.62%</td>
<td>69.95%</td>
<td>82.80%</td>
<td>99.05%</td>
</tr>
<tr>
<td>50</td>
<td>72.93%</td>
<td>65.63%</td>
<td>70.03%</td>
<td>75.52%</td>
<td>88.26%</td>
<td>99.40%</td>
</tr>
</tbody>
</table>

Table 2: Estimation accuracy

<table>
<thead>
<tr>
<th>Embedding rate (%)</th>
<th>Estimation accuracy of threshold ( T )</th>
</tr>
</thead>
<tbody>
<tr>
<td>5</td>
<td>97.50%</td>
</tr>
<tr>
<td>10</td>
<td>98.10%</td>
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<tr>
<td>20</td>
<td>98.25%</td>
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</tr>
<tr>
<td>40</td>
<td>99.05%</td>
</tr>
<tr>
<td>50</td>
<td>99.40%</td>
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</tbody>
</table>

Compared with the result of the experiment in Tab. 1, it can be seen that the proposed analytical algorithm based on histogram of absolute difference of adjacent pixels can effectively detect EALMR, and has accuracy rate at least 97.50% when detecting stego image with low embedding rate. From Tab. 2, the estimation accuracy of threshold \( T \) is consistent with EALMR detection accuracy of this proposed algorithm in Tab. 1. This is because the detection principle of the proposed algorithm is to determine whether the image to be tested has information embedded through EALMR by judging whether there is pulse distortion at the long tail of histogram of absolute difference of adjacent pixels, and the place of the distortion is \( T + 1 \). Therefore, so as long as it can detect that the image to be tested is EA stego image, threshold \( T \) will then be estimated.

For further analysis with the results of the experiment, the reason why the proposed steganalysis algorithm has a higher detection rate on EALMR than other airspace steganalysis algorithms is that the steganalysis
algorithm is based on EALMR itself as a starting point, aims to the influence from information embedding mechanism and data readjusting mechanism, which is the pulse distortion of long tail of histogram of absolute difference of adjacent pixels to make detection and analysis.

**Conclusion:**

This paper proposed Steganalysis algorithm based on histograms of the absolute difference of adjacent pixels to detect EALMR. This algorithm firstly analyzes the impact of information embedding mechanism and data readjusting mechanism in the EALMR on stego image, indicates that such influence brings obvious pulse distortion to the long tail of histogram of absolute difference of adjacent pixel of the stego image, and provides an effective analysis algorithm to detect EALMR. The corresponding experiment is made in view of the proposed algorithm, and the experiment results are analyzed. The result verifies the accuracy of this algorithm to be used to detect EALMR and better detection effect of this algorithm with low embedding rate than other steganalysis algorithms. In addition, based on further analysis, with this algorithm, the threshold T used when information is embedded into stego image can be predicted.

**REFERENCES**


